# **Raymarine**®

# ST40 Bidata Instrument Owner's Handbook

Document number: 81159-3 Date: March 2006 Preface i

# **Important information**

# Safety notices



**WARNING: Product installation & operation** 

This equipment must be installed and operated in accordance with the Raymarine instructions provided. Failure to do so could result in personal injury, damage to your boat and/or poor product performance.



WARNING: Electrical safety

Make sure you have switched off the power supply before you start installing this product.



**WARNING: Navigation aid** 

Although we have designed this product to be accurate and reliable, many factors can affect its performance. Therefore, it should serve only as an aid to navigation and should never replace commonsense and navigational judgement. Always maintain a permanent watch so you can respond to situations as they develop.

### **EMC conformance**

All Raymarine equipment and accessories are designed to the best industry standards for use in the recreational marine environment.

The design and manufacture of Raymarine equipment and accessories conform to the appropriate Electromagnetic Compatibility (EMC) standards, but correct installation is required to ensure that performance is not compromised.

# Waste from Electrical and Electronic Equipment (WEEE) Directive



The Waste from Electrical and Electronic Equipment (WEEE) Directive requires the recycling of waste electrical and electronic equipment. Whilst the WEEE Directive does not apply to some of Raymarine's products, we support its policy and ask you to be aware of how to dispose of this product.

The crossed out wheelie bin symbol, illustrated above, and found on our products signifies that this product should not be disposed of in general waste or landfill.

Please contact your local dealer, national distributor or Raymarine Technical Services for information on product disposal.

### **Handbook information**

To the best of our knowledge, the information in this handbook was correct when it went to press. However, Raymarine cannot accept liability for any inaccuracies or omissions it may contain.

In addition, our policy of continuous product improvement may change specifications without notice. Therefore, Raymarine cannot accept liability for any differences between the product and the handbook.

Preface iii

# **Contents**

Important informationi
WARNINGi
EMC conformance i
Handbook informationi
Prefacev
Parts suppliedvi
Chapter 1: Operation1
1.1 Introduction
Display1
1.2 Operating procedures
Display action
Silencing alarms
1.3 Alarms
Alarm indications
Shallow alarm7
Deep alarm7
Anchor alarms
Enabling/disabling alarms
Chapter 2: Maintenance and Fault Finding9
2.1 Maintenance
Servicing and safety9
Instrument
Transducer
Cabling
2.2 Fault finding
Preliminary procedures10
Fixing faults
Assistance

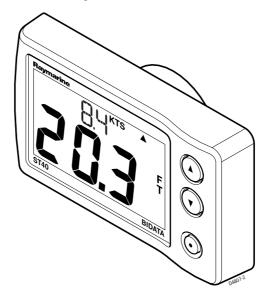
Chapter 3: Installation	15
3.1 Planning your installation	15
EMC installation guidelines	15
Suppression Ferrites	16
Connections to Other Equipment	16
Tools required	16
Site requirements	17
Transducers	17
Instrument	19
3.2 Procedures	20
Fitting transducers	20
Running transducer cable	20
Connections to the instrument	21
Stand-alone connections	22
SeaTalk connections	23
Fitting the instrument	23
Desktop Mounting Bracket	25
3.3 Calibration requirement	26
Chapter 4: Calibration	27
4.1 Introduction	27
EMC conformance	27
4.2 User calibration	27
Depth offsets	31
4.3 Intermediate calibration	31
4.4 Dealer calibration	32
Instrument Specification	35
Glossary	37
Index	39

Preface

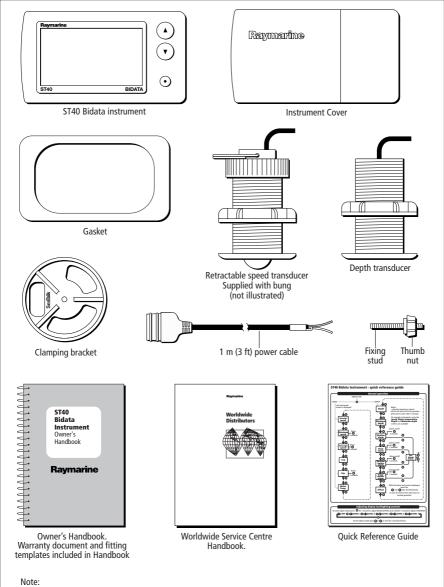
# **Preface**

Thank you for purchasing a Raymarine product. We are sure your ST40 instrument will give you many years of trouble-free operation.

This instrument is designed to provide reliable performance, even under the most demanding conditions.



# **Parts supplied**



The items shown here are supplied for an ST40 Bidata system. If an instrument is purchased separately, transducers are not included. If any item is not present, contact your Raymarine Dealer.

D4730-2

Chapter 1: Operation 1

# **Chapter 1: Operation**

### 1.1 Introduction

Your ST40 Bidata instrument:

- Provides speed information (current, maximum and average), in either knots (KTS), miles per hour (MPH) or kilometres per hour (KPH).
- Provides log and trip information. These are given in either nautical miles (NM), statute miles (M) or kilometres (KM).
- Provides water temperature information. This is given in either degrees Celsius (°C) or degrees Fahrenheit (°F).
- Provides depth information in either feet (FT), metres (M) or fathoms (FA).
- Records the minimum depth encountered during the period it is switched on. You can reset this at any time.
- Enables you to define alarm thresholds for shallow water, deep water, shallow anchor and deep anchor.
- Enables you to see what offset is applied to the depth reading.

**Note:** The required speed, distance, depth and water temperature units are selected during User calibration (see Chapter 4, Calibration).

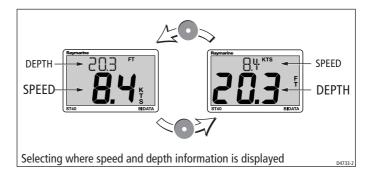
### **CAUTION**

Your instrument is calibrated to factory (default) settings when first supplied and must therefore be calibrated before use, to ensure optimum performance on your vessel. Do NOT use the instrument until the calibration procedures have been satisfactorily completed, using the procedures in *Chapter 4*, *Calibration*.

Coloured bezel and Desktop Mounting Bracket options are available for your ST40 instrument. Contact your Raymarine dealer for further information.

# **Display**

The ST40 Bidata display comprises upper and lower data areas, each of which shows either depth or speed information, selected as shown in the following illustration.



# 1.2 Operating procedures

Operating information is presented in flow chart form. The flow charts show the various operating screens and key presses necessary to carry out the various instrument functions. Key presses are momentary unless otherwise stated. Note that:

- Up/down depth-trend arrows are displayed, if the seabed is rising or falling at a significant rate.
- The minimum depth reading is reset to zero at power up.
- The maximum speed reading is reset to zero at power up.
- The average speed reading is reset to zero at power up.
- The Log screen shows the total distance covered by the vessel since the ST40 Bidata instrument was fitted.
- The trip reading is reset to zero at power up.

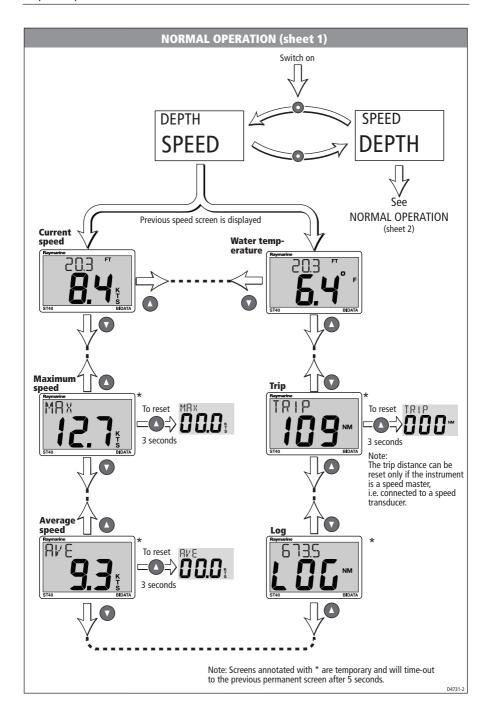
# **Display action**

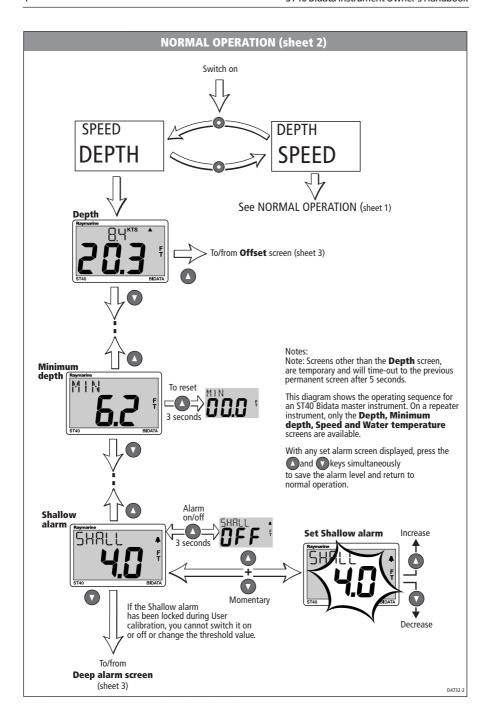
During normal operation (see *Normal operation* flow charts), the **Speed**, **Depth** and **Water temperature** screens are permanent screens, i.e. once one of these is selected, it will remain until another screen is manually selected. All other screens are temporary and after 5 seconds, will time out to the permanent screen which was last displayed for 5 seconds or more.

# Silencing alarms

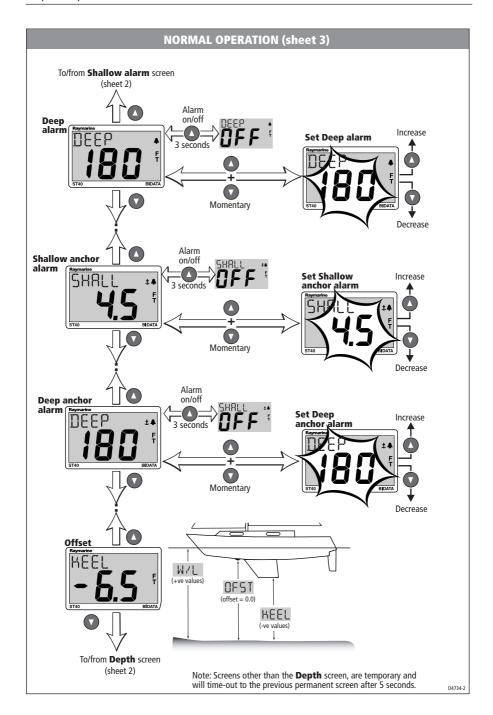
To silence an alarm (see the *Alarms* section, later in this chapter), momentarily press any one of the instrument keys.

Chapter 1: Operation 3



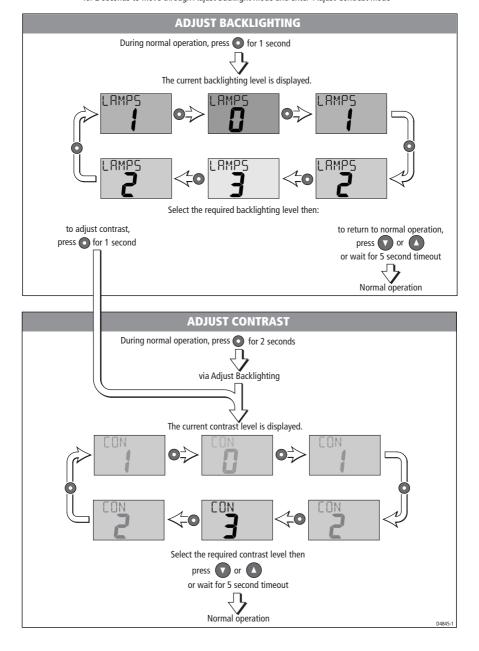


Chapter 1: Operation 5



# **Adjusting display backlighting and contrast**

Hold down of for 1 second to enter Adjust Backlight mode
for 2 seconds to move through Adjust Backlight mode and enter Adjust Contrast mode

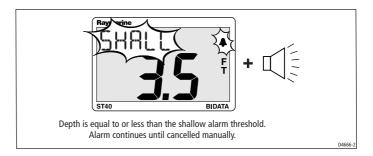


Chapter 1: Operation 7

## 1.3 Alarms

# **Alarm indications**

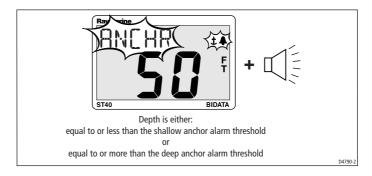
### **Shallow alarm**



## **Deep alarm**



### **Anchor alarms**



# **Enabling/disabling alarms**

You can enable or disable any alarm function (i.e. switch it on or off) by selecting the relevant alarm screen (see *Normal operation*) and holding down the  $\triangle$  key for 3 seconds (toggle action).

# **Chapter 2: Maintenance and Fault Finding**

### 2.1 Maintenance

# **Servicing and safety**

- Raymarine equipment should be serviced only by authorised Raymarine service technicians. They will ensure that service procedures and replacement parts used will not affect performance. There are no user-serviceable parts in any Raymarine product.
- Some products generate high voltages, so never handle the cables/ connectors when power is being supplied to the equipment.
- When powered up, all electrical equipment produces
  electromagnetic fields. These can cause adjacent pieces of electrical
  equipment to interact with one another, with a consequent adverse
  affect on operation. In order to minimise these effects and enable
  you to get the best possible performance from your Raymarine
  equipment, guidelines are given in the installation instructions, to
  enable you to ensure minimum interaction between different items
  of equipment, i.e. ensure optimum Electromagnetic Compatibility
  (EMC).
- Always report any EMC-related problem to your nearest Raymarine dealer. We will use any such information to improve our quality standards.
- In some installations, it may not be possible to prevent the equipment from being affected by external influences. In general this will not damage the equipment but it can lead to spurious resetting action, or momentarily may result in faulty operation.
- Always switch off the power to Raymarine equipment before working on it.

When requesting service, please quote equipment Type, Model Number, Serial Number and, if possible, Software Release Issue. The Software Release Issue can be ascertained by means of the Intermediate Calibration facility, see *Chapter 4*, *Calibration*.

### **Instrument**

Certain atmospheric conditions may cause a small amount of condensation to form on the instrument window. This will not harm the instrument and will clear after the instrument has been switched on for a short period.

Periodically clean your ST40 instrument with a soft damp cloth. Do NOT use chemical or abrasive materials to clean the instrument.

### **Transducers**

Refer to the Installation and Maintenance instructions supplied with the transducers.

# **Cabling**

Examine all cables for chafing or other damage to the outer shield and, where necessary, replace and re-secure.

# 2.2 Fault finding

# **Preliminary procedures**

If you appear to have a problem, first check the security of the connections at the rear of the instrument and reconnect any that are loose.

Changes in the electronic environment may adversely affect the operation of your ST40 equipment. Typical examples of such changes are:

- Electrical equipment has recently been installed or moved aboard your vessel.
- You are in the vicinity of another vessel or shore station emitting radio signals.

# **Fixing faults**

All Raymarine products are subjected to comprehensive test and quality assurance programmes prior to packing and shipping. However, if a fault occurs, the following guidelines may help to identify and rectify the problem.

### **Low battery**



#### Action

Recharge your vessel's battery as soon as possible

### **Display blank**



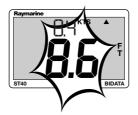
### **Action**

Check fuse/circuit breaker.

Check power supply.

Check SeaTalk cabling and connector security.

# Depth reading flashes when under way



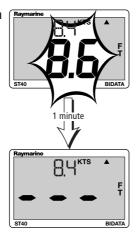
OR



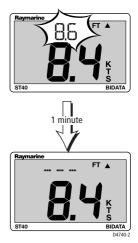
### **Action**

Ensure that reading stabilises when clear of disturbed water, e.g. boat wakes, propeller wash etc.

## No depth information



OR

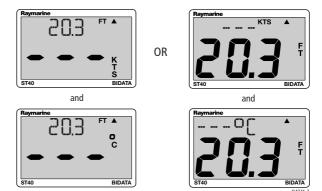


### **Action**

Check the condition of the depth transducer cable and the security of the connections.

Could also be due to weed growing on the transducer face.

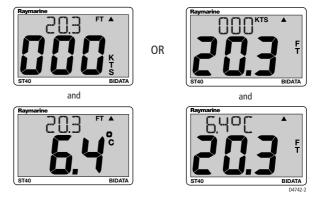
# No speed or temperature information



### Action

Check the condition of the speed transducer cable and the security of the connections.

### No speed information but temperature information is present



# Action CAUTION

If you need to remove the transducer insert, have the transducer bung to hand and secure it in the transducer body immediately after the insert has been removed, to prevent excessive ingress of water.

The speed transducer paddle wheel may be fouled. Clean the paddle wheel.

### SeaTalk information not being transferred between instruments

For example, backlighting level changes implemented at one instrument do not affect other instruments

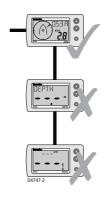
### Action

Check security of SeaTalk connections between instruments.

Check condition of SeaTalk cables.

Isolate faulty instrument by disconnecting instruments one by one.

# A group of SeaTalk instruments not working



### **Action**

Check the security of SeaTalk connectors between functioning and non-functioning instruments.

## **Assistance**

If you are unable to rectify any problem, please contact your local Raymarine Dealer for assistance.

Chapter 3: Installation 15

# **Chapter 3: Installation**

This chapter describes how to install the ST40 Bidata instrument, and associated transducers. The transducers are fitted in the hull of the vessel and is connected to the rear of the instrument.

# 3.1 Planning your installation

Determine the best positions for both transducer and instrument, such that the *EMC installation guidelines* and the *Site requirements* (below) are satisfied.

# **EMC installation guidelines**

All Raymarine equipment and accessories are designed to the best industry standards for use in the leisure marine environment.

Their design and manufacture conform to the appropriate Electromagnetic Compatibility (EMC) standards, but correct installation is required to ensure that performance is not compromised. Although every effort has been taken to ensure that they will perform under all conditions, it is important to understand what factors could affect the operation of the product.

The guidelines given here describe the conditions for optimum EMC performance, but it is recognised that it may not be possible to meet all of these conditions in all situations. To ensure the best possible conditions for EMC performance within the constraints imposed by any location, always ensure the maximum separation possible between different items of electrical equipment.

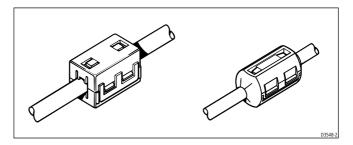
For **optimum** EMC performance, it is recommended that **wherever possible**:

- All Raymarine equipment and cables connected to it are:
  - At least 1 m (3 feet) from any equipment transmitting or cables carrying radio signals e.g. VHF radios, cables and antennas. In the case of SSB radios, the distance should be increased to 2 m (7 ft).
  - More than 2 m (7 ft) from the path of a radar beam. A radar beam can normally be assumed to spread 20 degrees above and below the radiating element.

- The equipment is supplied from a different battery from that used for
  engine start. Voltage drops below 10 V in the power supply to our
  products, and starter motor transients, can cause the equipment to
  reset. This will not damage the equipment, but may cause the loss of
  some information and may change the operating mode.
- Raymarine specified cables are used at all times. Cutting and rejoining these cables can compromise EMC performance and so must be avoided unless doing so is detailed in the installation manual.
- If a suppression ferrite is attached to a cable, this ferrite should not be removed. If the ferrite needs to be removed during installation it must be reassembled in the same position.

### **Suppression Ferrites**

The following illustration shows typical cable suppression ferrites fitted to Raymarine equipment. Always use the ferrites supplied by Raymarine.



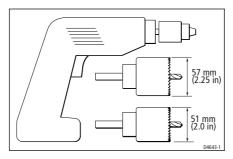
### **Connections to Other Equipment**

If your Raymarine equipment is going to be connected to other equipment using a cable not supplied by Raymarine, a suppression ferrite MUST always be fitted to the cable close to the Raymarine unit.

## **Tools required**

The tools required for fitting the standard ST40 instrument system are shown in the following illustration.

Chapter 3: Installation 17



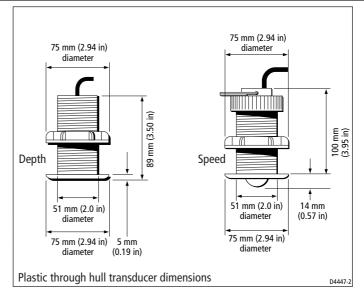
**Note:** If you intend fitting a nonstandard transducer, extra tools may be required

# **Site requirements**

### **Transducers**

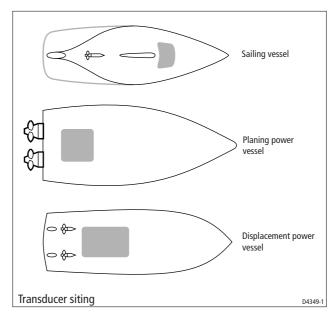
The transducer types required for the various hull types are as follows:

Hull material	Speed transducer	Depth transducer
GRP Steel Aluminium	M78712 Through hull plastic (supplied as standard)	M78713 through hull plastic (supplied as standard) or M78718 Retractable through hull
Wood	M78716 Through hull bronze	M78714 Through hull bronze



Other transducer types are available for specific requirements. For further details, contact your local Raymarine dealer.

The transducers should be sited within the clear water flow areas indicated by the shaded areas below.

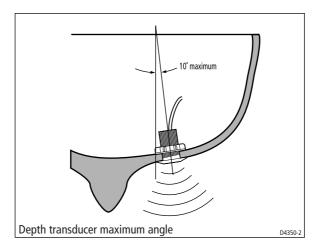


Each transducer should also:

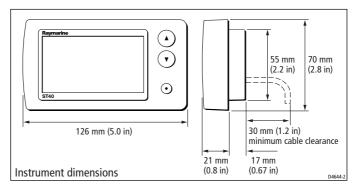
- Be ahead of the propellers (by a minimum of 10% of the water line length).
- Be at least 150 mm (6 in) away from the keel (ideally ahead of the keel if a sailing yacht).
- Be as near as possible to the centre line of the vessel.
- Be clear of other through-hull fittings or projections.
- Have sufficient clearance inside the hull to fit the nut.
- Have 100 mm (4 in) of headroom to allow for withdrawal.

In addition to the above requirements, the depth transducer must be mounted within  $10^{0}$  of the vertical, forward, aft and athwart ships.

Chapter 3: Installation 19



#### Instrument



### **CAUTION:**

The presence of moisture at the rear of the instrument could cause damage either by entering the instrument through the breathing hole or by coming into contact with the electrical connectors.

Each instrument must be positioned where:

- It is easily read by the helmsman or navigator
- It is protected against physical damage
- It is at least 230 mm (9 in) from a compass
- There is reasonable rear access for installation and servicing
- The rear of the instrument is protected from water.

### 3.2 Procedures

Adapt these procedures as appropriate, to suit your individual requirement.

### **CAUTION:**

Where it is necessary to cut holes (e.g. for cable routing and instrument mounting), ensure that these will not cause a hazard by weakening critical parts of the vessel's structure. If in doubt, seek the advice of a reputable boat builder.

# **Fitting transducers**

Instructions for installing and maintaining the speed and depth transducers are packed with them. Before attempting to install the transducers, read these instructions and the *Site requirements* for transducers described in this Chapter.

### **Running transducer cable**

Each transducer type has a 9 m (30 ft) cable fitted with spade terminals for connection to the ST40 Bidata instrument. Observing the following guidelines, run the cable to the instrument:

- If the cable has to be fed through the deck, always use a good quality deck gland.
- Where cables are fed through holes, always use grommets to prevent chafing.
- Secure long cable runs so they do not present a hazard.
- Wherever possible, route the cable away from fluorescent lights, engines, radio transmitting equipment, as these may cause interference.

**Important point:** Do NOT shorten the cable from the depth transducer as this will seriously degrade transducer performance.

Chapter 3: Installation 21

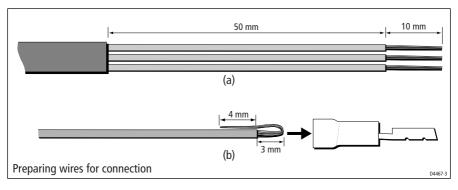
### **Connections to the instrument**

You can connect your instrument:

- Directly to the speed and depth transducers as a stand-alone master instrument. When connected in this manner, the instrument must be connected to a suitable power source using the 1 m (3 ft) power cable provided.
- As part of a SeaTalk system either as a repeater or, with a transducer also connected as a system master. To connect to SeaTalk, you will need an additional SeaTalk Interconnection Kit (Part No. E25028).
   When connected in this manner, power can be provided from the SeaTalk bus (e.g. from the autopilot).

You can also connect the instrument to the speed and depth transducers and to SeaTalk. When thus connected, the instrument will be the master speed and depth instrument for the SeaTalk system.

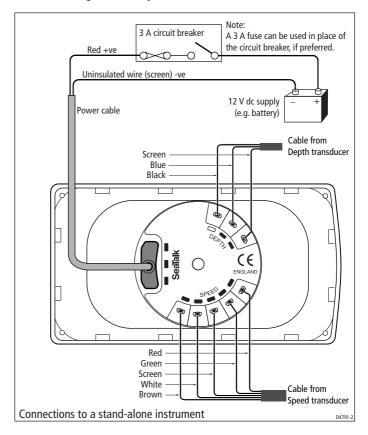
If it is necessary to fit spade connectors to the transducer cable, do so as shown in the following illustration. Prepare the cable, as at (a), and fit the spade connectors, as at (b). When fitting each spade connector, ensure that wire strands do not extend beyond the rear of the spade connector insulation.



### **Stand-alone connections**

### **CAUTION**

Ensure that the power supply for each stand-alone ST40 instrument is protected by a 3 A fuse or circuit breaker.

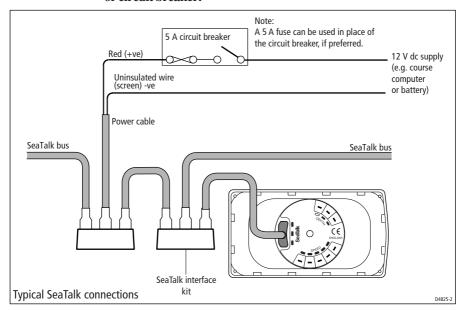


Chapter 3: Installation 23

### **SeaTalk connections**

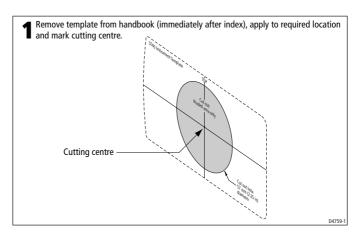
### **CAUTION**

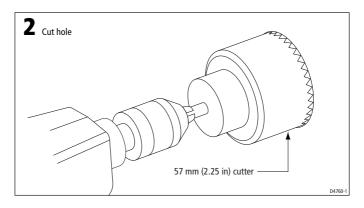
When instruments are connected to SeaTalk, ensure that the power supply for the SeaTalk 12 V line is protected by a 5 A fuse or circuit breaker.

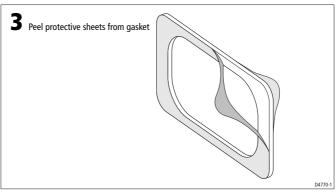


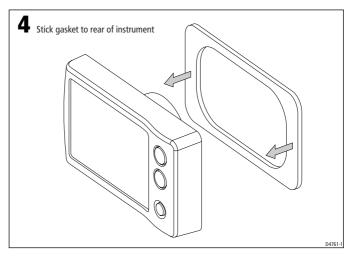
# Fitting the instrument

Fit your ST40 instrument as shown in the following illustrations.

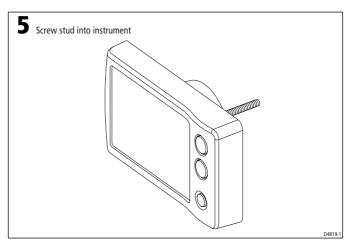


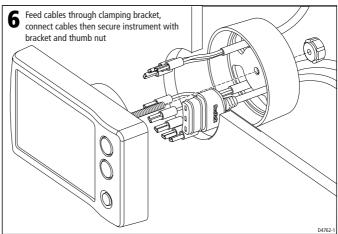






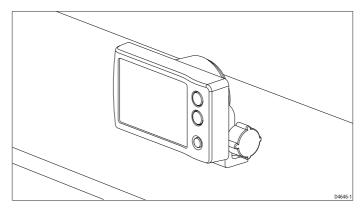
Chapter 3: Installation 25





# **Desktop Mounting Bracket**

An optional Desktop Mounting Bracket (Part No. E25024) enables you to mount your ST40 instrument in locations where other forms of mounting are impractical.



To bracket mount your ST40 instrument, do so in accordance with the *Instruction Sheet*, which is included with the Desktop Mounting Bracket.

# 3.3 Calibration requirement

Once installation is complete and before you use your instrument, carry out the calibration procedures detailed in *Chapter 4*, *Calibration*.

Chapter 4: Calibration 27

# **Chapter 4: Calibration**

## 4.1 Introduction

The procedures in this Chapter must be carried out before the equipment is used operationally, to optimise the performance of the instrument with the vessel.

Calibration information is presented in flow chart form. The flow charts show the various calibration screens and key presses necessary to carry out calibration. All key presses are momentary unless otherwise stated.

### **EMC conformance**

 Always check the installation before going to sea to make sure that it is not affected by radio transmissions, engine starting etc.

## 4.2 User calibration

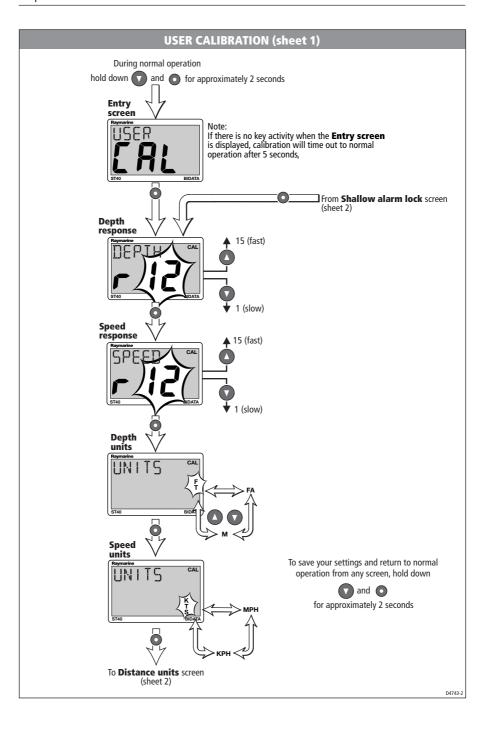
User calibration enables you to:

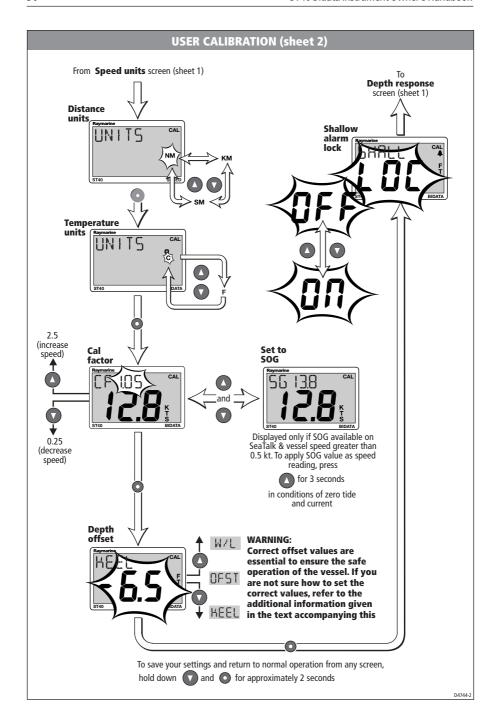
- Set the required units for speed readings. Either KTS (knots), MPH (miles per hour) or KPH (kilometres per hour).
- Select temperature units. Either °C or °F, as required.
- Set the speed display response. Use higher response values when boating in conditions requiring rapid updates of the current speed (e.g. competition sailing or on power boats). Use slower response values when you require an average speed over a longer period of time (e.g. when cruising, especially in heavy seas).
- Set the correct speed reading, either by using a Cal factor screen to
  adjust the calibration factor, or by applying Speed Over Ground
  (SOG) as the current speed. Your vessel must be moving at 0.5 KTS
  or more and be receiving SeaTalk SOG data, to enable SOG to be
  applied as the current speed. This should be done only in conditions
  of zero tide and current.
- Set the depth display response. Use higher response values when boating in conditions requiring rapid updates of depth information (e.g. inshore, especially when travelling at high speed). Use slower response values when you require an average depth over a longer period of time (e.g. deep sea cruising).
- Set the required units for depth readings. Either FT (feet), M (metres) or FA (fathoms).

- Set the required depth offset.
- Lock the shallow alarm, to prevent unauthorised changes during normal operation.

Power up the instrument then follow the procedure in the User calibration flow diagram. This diagram shows the User calibration sequence for an ST40 Bidata operating as a master instrument for both speed and depth .

Chapter 4: Calibration 29





Chapter 4: Calibration 31

### **Depth offsets**

#### **WARNING:**

The use of incorrect offset values could result in misleading depth information being displayed with a consequent risk of running aground.

The depth offset screen enables you to determine the exact point on the vessel from which depths are measured. This point can be:

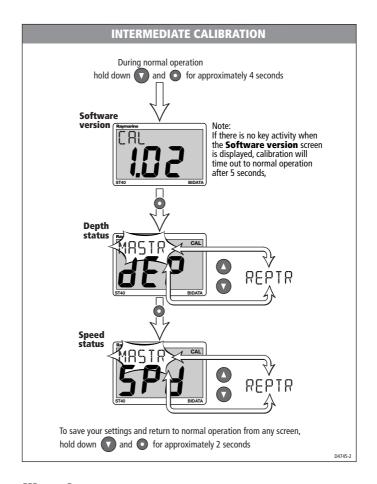
- The transducer. Set offset to zero. With zero offset applied, the screen header is OFST.
- The bottom of the keel. Set a negative offset equal to the vertical distance between the transducer position and the bottom of the keel. With a negative offset applied, the screen header is KEEL.
- The water line. Set a positive offset equal to the vertical distance between the transducer position and the water line. With a positive offset applied, the screen header is W/L.

#### 4.3 Intermediate calibration

Intermediate calibration enables you to:

- Check the instrument software version.
- Check and if necessary set, the instrument status either MASTR (master) or REPTR (repeater), for both speed and depth.

Follow the procedure in the *Intermediate calibration* flow diagram.



#### **4.4 Dealer calibration**

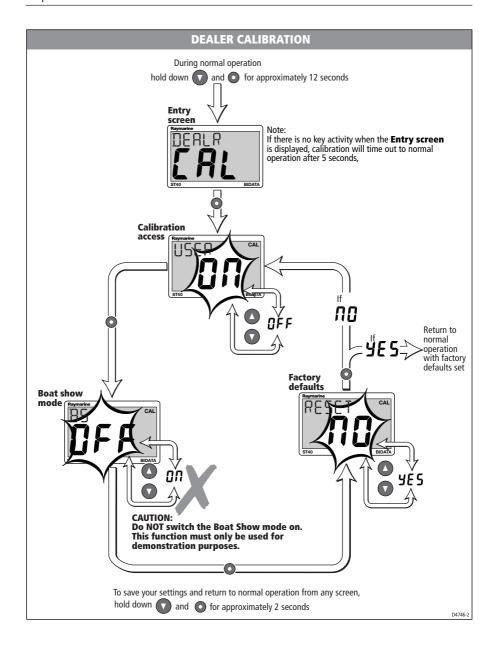
Dealer calibration enables you to set:

- User calibration on/off.
- · Boat show mode on/off.

Dealer calibration also gives access to the **Factory defaults** screen. This enables you to reapply the factory settings if you want to reset the instrument to a known operating condition.

Follow the procedure in the *Dealer calibration* flow diagram.

Chapter 4: Calibration 33



## **Instrument Specification**

**Supply voltage:** 10 V to 16 V dc.

**Current consumption (12 V supply):** 35 mA typical.

70 mA with maximum backlighting.

**Operating temperature:**  $0^{\circ}\text{C to +}70^{\circ}\text{C}.$ 

**Interfaces:** SeaTalk.

**Overall dimensions:** 126 mm x 70 mm x 38 mm

(5.00 inches x 2.80 inches x 1.55 inches).

**Boss diameter:** 55 mm (2.20 inches).

**Speed range:** 0 to 99.9 knots.

**Log range:** 0 to 99999.

**Trip reading range:** 0 to 999 nautical miles.

**Temperature reading range:**  $-10^{\circ}\text{C to} + 40^{\circ}\text{C}$ .

**Depth range:** 0 to 400 feet.

**Shallow depth alarm:** 0 to 29 feet.

**Deep depth alarm:** 30 to 400 feet.

**Shallow anchor alarm:** 1 to 250 feet.

**Deep anchor alarm:** 10 to 400 feet.

Approvals:

**CE - conforms to** 89/336/EC(EMC), EN60945.

94/25/EC(RCD), EN28846 (applies to

transducer only).

Glossary 37

### **Glossary**

**Cal factor** Calibration factor. Used in the ST40 Speed and Bidata instruments to

ensure the current speed reading is the actual speed. Values are from 0.25

(reduce speed reading) to 2.5 (increase speed reading).

**EMC** Electromagnetic Compatibility.

**FA** Fathoms.

**FT** Feet.

**KEEL** When displayed on the **Offset** screen (during normal operation), or the

**Depth offset** screen (during User calibration), indicates that a negative

depth offset is set.

**KPH** Kilometres per hour.

**KTS** Knots.

M Metres.

**MPH** Miles per hour.

**OFST** When displayed on the **Offset** screen (during normal operation), or the

**Depth offset** screen (during User calibration), indicates that a depth

offset value of 0 is set.

**Response** The rate at which an instrument responds to changes in speed and depth.

Values are from 1 (slow response) to 15 (fast response).

**SeaTalk** SeaTalk is a proprietary Raymarine system which links different

compatible products, to provide a single, integrated navigational system. SeaTalk can also communicate with non-SeaTalk equipment using the internationally- accepted National Marine Electronics Association (NMEA) protocol. Contact your Raymarine dealer for details.

W/L When displayed on the **Offset** screen (during normal operation), or the

**Depth offset** screen (during User calibration), indicates that a positive

depth offset is set.

Index 39

# Index

A	Dieplay
Alarms 7–8	Display backlighting 6
enable/disable 8	contrast 6
indications 7	
ranges 35	selecting speed or data display
setting thresholds 4–5	E
silencing 2	EMC
switching on and off 4–5	conformance i, 27
Average speed reset 2, 3	installation guidelines 15–16
В	F
Backlighting 6	Factory defaults 32
Boat show mode 32	Fault finding 10
_	assistance 13
C	blank display 11
Calibration 27–33	depth reading flashing 11
Dealer 32–33	low battery 10
Intermediate 31–32	no depth information 11
setting appropriate response val-	no speed information 12
ues 27	no speed or temperature informa-
setting user access 33	tion 12
User 27–31	SeaTalk problems 13
User calibration screen sequences 31	_
Calibration requirement 1, 26	1
Cleaning the instrument 10 Condensation 9	Installation 15–26
	connecting the instrument 21
Connecting the instrument 21	EMC guidelines 15
Contrast 6	fitting the instrument 23–26
Current consumption 35	planning 15–19
D	site requirements 17–20
Dealer calibration 32–33	tools required 16–17
Depth	transducers 20
alarms 4–5	Instrument
appropriate response values 27	cleaning 10
offset 5, 28, 30, 31	condensation 9
range 35	connecting 21
reading flashing 11	current consumption 35
response 27, 29	fitting 23–26
units 27	site requirements 19
Desktop Mounting Bracket 25–26	status (master or repeater) 31
Dimensions 35	supply voltage 35 Intermediate calibration 31–32
	intermediate campration 31-32

L				
Log range 35 Log distance 2 Low battery indication 10  M Maintenance 9–10 Maximum speed reset 2, 3 Minimum depth reset 2, 4	Site requirements 17–20 instrument 19 transducers 17–20 Software version 31 Specifications 35 Speed appropriate response values 27 calibration factor 37 range 35 response 27			
Normal operation 3–6	units 29			
O Offset 5, 28, 30, 31 Operation 1–8  P Panel lighting 6 Parts supplied vi	T Temperature reading range 35 Transducers fitting 20 site requirements 17–20 Trip distance range 35 Trip distance reset 3			
Reset average speed 2, 3 maximum speed 2, 3 minimum depth 2, 4 trip distance 3 Response values depth 27 speed 27	User calibration 27–31 screen sequences 31  V Voltage 35			
Servicing and safety 9 Setting alarm thresholds 4–5 backlighting 6 calibration factor 30 contrast 6 correct speed 30 depth offset 30–31 depth response 29 depth units 29 shallow alarm lock 29 speed units 29 Shallow alarm lock 29 Shallow alarm lock 29				

